



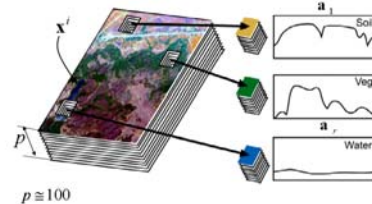
# Hyperspectral Channel Reduction For Local Anomaly Detection

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## Outline

- Designing *Multispectral Filters* (MF) for *Anomaly Detection* algorithms
- Filter design is based on processing *Hyperspectral Images*
- MF are obtained by replacing subsets of adjacent spectral bands by their means
- Partition is optimal in terms of minimizing the *Maximum of Mahalanobis Norms (MXMN)*
- Improved ROC compared to  $\ell_2$ -based alternatives using RX
- Real Data results are presented

## Hyperspectral Imaging



## From Hyperspectral to Multispectral

- Given hyperspectral images, partition spectra into a number of bands  $K$
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- Which partition is best for detecting anomalies for a given  $K$ ?

## Problem Statement

- Determine a vector of  $K$  breakpoints  $\mathbf{b}_K = \{b_1, \dots, b_K\}$
- Corresponding to  $K - 1$  contiguous intervals  $I_k = [b_k, b_{k+1})$
- Producing a set of constants at each pixel  $j$   $\mu_{k,j} = \frac{1}{|I_k|} \sum_{i \in I_k} x_{i,j}$
- Such that a cost function  $J(\mathbf{b}_K, \mathbf{X})$  is minimized

## Fast Hyperspectral Feature Reduction (FFR) [1]

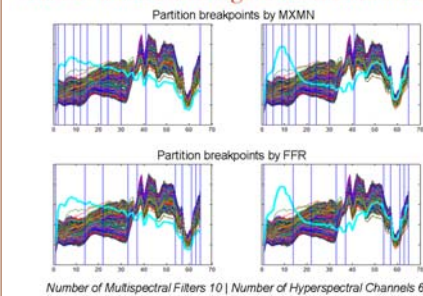
- Error vector at interval  $k$  in pixel  $j$   $\mathbf{e}_{k,j} \triangleq \{(x_{i,j} - \mu_{k,j}) : i \in I_k\}$
- Squared error at pixel  $j$   $e_j^2 \triangleq \sum_{k=1}^{K-1} \|\mathbf{e}_{k,j}\|^2$
- Sum of squared error cost  $J(\mathbf{b}_K, \mathbf{X}) \triangleq \sum_{j=1}^N e_j^2$ 
  - Is not sensitive enough to anomaly contributions
  - Partition is governed by the background process
  - Anomalies are misrepresented

[1] A. C. Jensen and A. S. Solberg, "Fast Hyperspectral Feature Reduction Using Piecewise Constant Function Approximations," IEEE Geoscience and Remote Sensing Letters, vol. 4, no. 4, Oct. 2007.

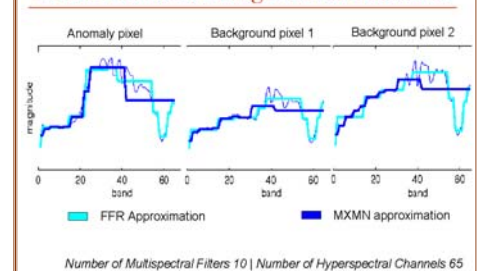
## The proposed Maximum of Mahalanobis Norms (MXMN)

- Error vector at interval  $k$  in pixel  $j$   $\mathbf{e}_{k,j} \triangleq \{(x_{i,j} - \mu_{k,j}) : i \in I_k\}$
  - Error covariance matrix in an interval  $k$   $\Sigma_k$
  - Mahalanobis norm of error  $j$  in an interval  $k$   $G(\mathbf{e}_{k,j}) = \sqrt{\mathbf{e}_{k,j}^T \Sigma_k^{-1} \mathbf{e}_{k,j}}$
  - Anomaly sensitive cost in an interval  $k$   $D_k = \max_{j=1}^N G(\mathbf{e}_{j,k})$
  - Maximum of costs in all intervals  $J(\mathbf{b}_K, \mathbf{X}) = \max_{k=1}^K D_k$
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- Allows capturing misrepresented anomaly contributions
  - Eliminates heavy tails of errors pdf
  - The more "Gaussian" interval is, the coarser is the partition in it

## Partition breakpoints: MXMN vs. FFR



## Partition Examples: MXMN vs. FFR



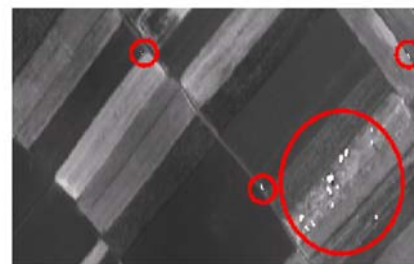
## RX – a benchmark Anomaly Detection Algorithm

- Background model pdf  $p(\mathbf{x})$
- Hypotheses:  $H_0 : \mathbf{x} \sim p(\mathbf{x})$ ,  $H_1 : \mathbf{x} - \mathbf{a} \sim p(\mathbf{x})$
- GLRT - Reed Xiaoli (RX)  $L(\mathbf{x}) = -\log p(\mathbf{x}) \stackrel{H_1}{\geq} \eta$
- Gaussian GLRT  $p(\mathbf{x}) = N(\mathbf{x}|\mu, \Gamma)$ 

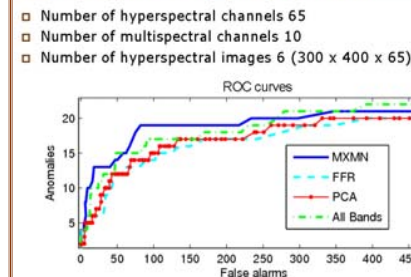
$$L(\mathbf{x}) = (\mathbf{x} - \mu)^T \Gamma^{-1} (\mathbf{x} - \mu) \stackrel{H_1}{\geq} \eta$$

Mahalanobis distance

## Example: HS channel image with anomalies



## ROC curves by applying RX



## Conclusion

- A new criterion (MXMN) was proposed for Multispectral filter design
- MXMN allows capturing anomalies well
  - In terms of hyperspectral partition granularity
  - In terms of Rx performance (ROC curves)
- In the presented example, the anomaly representation performance was good even after training on data without anomalies
- MXMN was evaluated on real data images